# Nested Error Non-parametric Unit Level Model performance in the context of empirical Bayes (EB) approach 

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#### Abstract

In this paper, we assess the performance of the proposed model compared with the standard unit-level model, the performance of both models were evaluated in the case of skewed data. The empirical Bayes (EB) estimates obtained under both models were compared through different criteria proposed by the panel on small area estimates of population and income set up by the United States Committee on National Statistics in 1978 and the proposed model was found to fit better than the standard one. The MSE for both models were checked using the bootstrap technique and the proposed model win over the standard model at each bootstrap iterations.


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## 1 Introduction

In statistical inference, the empirical Bayes methods are procedures used when the prior distribution is not known but estimated from data. In small area estimation, the empirical Bayes methods have been proven to be efficient data-analysis tools when data violent some normality assumptions. There are used in the estimation of the nonlinear parameter under the basic unit model and quite a number of application to poverty mapping[6]. The empirical Bayes model is much richer than either the classical or the ordinary Bayes model and often provides superior estimates of parameters[8]. In this paper, we assess the performance of the proposed model [5] comparing with the basic unitlevel model proposed by Fuller, Battese and Harter,1988)[7]. To achieve our goal, we examined the empirical Bayes estimates for both models throughout two general standpoints: the accuracy of point estimates and Mean Square Error (MSE) of the estimates. The former was checked through the relative errors and absolute relative errors of the empirical Bayes estimates, the later was estimated by a bootstrap procedure similar to the the bootstrap algorithm proposed by[3].

## 2 Empirical Bayes (EB) approaches

### 2.1 Basic Unit level Model

In small area estimation, a basic unit-level model(FBH) is based on unit level auxiliary variables i.e $X_{i j}=\left(x_{i j 1}, \cdots, x_{i j p}\right)^{T}$ are available for population element $j$ in each small area $i$.These variables are related to unit level values of response $y_{i j}$ through a nested error linear regression model[6].

$$
\begin{equation*}
y_{i j}=x_{i j}^{T} \beta+v_{i}+e_{i j} \tag{1}
\end{equation*}
$$

where $y_{i j}$ is the response of unit $j, j=1,2, \cdots, N_{i}$ in area $i, i=1,2, \cdots, m$. $x_{i j}$ is the vector of auxiliary variables, $\beta$ is the vector of the regression parameters, the random effect $v_{i}$ represents the effect of area characteristics are not accounted for by auxiliary variables $X_{i j}$ and $e_{i j}$ the individual unit error term.

The area effects $v_{i}$ are assumed independent with mean zero and variance $\sigma_{u}^{2}$, The errors $e_{i j}$ are independent with mean zero and variance $\sigma_{e}^{2}$. In addition, the $v_{i}{ }^{\prime} \mathrm{s}$ and $e_{i j}{ }^{\prime}$ s are assumed to be independent.

The small area parameter of interest, $\theta_{i}$, may be approximated by

$$
\begin{equation*}
\theta_{i}=\bar{X}_{i}^{T} \beta+v_{i}, \quad i=1, \cdots, m . \tag{2}
\end{equation*}
$$

assuming that $N_{i}$ is large, where $\bar{X}_{i}$ is the average vector of population of the $x_{i j}$ for the ith area, that is, $\bar{X}_{i}=\sum_{j=1}^{N_{i}} x_{i j} / N_{i}$. The sample data $\left\{y_{i j}, x_{i j}, j=\right.$ $\left.1, \cdots, n_{i}, i=1, \cdots, m\right\}$ are assumed to obey model 1, i.e.,

$$
\begin{equation*}
y_{i j}=x_{i j}^{T} \beta+v_{i}+e_{i j}, j=1, \cdots, n_{i}, \quad i=1, \cdots, m \tag{3}
\end{equation*}
$$

where $n_{i}$ is the sample size in the $i t h$ small area. This implies that the selection bias is absent. For a proof of this absence bias, see (Rao, 2003). Assuming that $v_{i} \sim \mathcal{N}\left(0, \sigma_{u}^{2}\right), i=1, \cdots, m$ and expressing $y_{i j} \mid \beta, v_{i}, \sigma_{e}^{2} \sim \mathcal{N}\left(x_{i j}^{T} \beta+v_{i}, \sigma_{e}^{2}\right), j=$ $1, \cdots, n_{i}, i=1, \cdots, m$, we have the distribution of $v_{i}$ from the unit-level model 3 conditional on $y_{i j}, \beta, \sigma_{u}^{2}$ and $\sigma_{e}^{2}$ as

$$
v_{i} \mid y_{i j}, \beta, \sigma_{u}^{2}, \sigma_{e}^{2} \sim \mathcal{N}\left(\Omega_{i}\left(\bar{y}_{i}-\bar{x}_{i}^{T} \beta\right), \Omega_{i} \frac{\sigma_{e}^{2}}{n_{i}}\right)
$$

where $\Omega_{i}=\sigma_{u}^{2} /\left(\sigma_{u}^{2}+n_{i}^{-1} \sigma_{e}^{2}\right),\left(\bar{y}_{i}, \bar{x}_{i}\right)$ are the sample means for the $i^{t} h$ area and the regression coefficient are obtained by using the relation $\beta=\left(X^{T} \Sigma^{-1} X\right)^{-1} X^{T} \Sigma^{-1} y$. Therefore,

$$
\begin{equation*}
\mathbb{E}\left[y_{i j}, \beta, \sigma_{u}^{2}, \sigma_{e}^{2}\right]=\Omega_{i}\left(\bar{y}_{i}-\bar{x}_{i}^{T} \beta\right) \tag{4}
\end{equation*}
$$

Using equation 2 and 4 , we get the Bayes predictor of $\theta_{i}, \theta_{i}^{B}$ as

$$
\begin{align*}
\theta_{i}^{B} & =\mathbb{E}\left[\theta_{i} \mid y_{i j}, \beta, \sigma_{u}^{2}, \sigma_{e}^{2}\right] \\
& =\left(\bar{X}_{i}^{T} \beta+\Omega_{i}\left(\bar{y}_{i}-\bar{x}_{i}^{T} \beta\right)\right.  \tag{5}\\
& =\left(1-\Omega_{i}\right) \bar{X}_{i}^{T} \beta+\Omega_{i}\left[\bar{y}_{i}+\left(\bar{X}_{i}-\bar{x}_{i}\right)^{T} \beta\right]
\end{align*}
$$

Replacing $\beta, \quad \sigma_{u}^{2}$ and $\sigma_{e}^{2}$ by $\hat{\beta}, \quad \hat{\sigma}_{u}^{2}$ and $\hat{\sigma}_{e}^{2}$ respectively we obtain the Empirical Bayes predictor of $\theta_{i}, \theta_{i}^{E B}$

$$
\begin{equation*}
\theta_{i}^{E B}=\left(1-\hat{\Omega}_{i}\right) \bar{X}_{i}^{T} \hat{\beta}+\hat{\Omega}_{i}\left[\bar{y}_{i}+\left(\bar{X}_{i}-\bar{x}_{i}\right)^{T} \hat{\beta}\right] \tag{6}
\end{equation*}
$$

where $\hat{\Omega}_{i}=\hat{\sigma}_{u}^{2} /\left(\hat{\sigma}_{u}^{2}+n_{i}^{-1} \hat{\sigma}_{e}^{2}\right)$ and $\hat{\beta}=\left(X^{T} \hat{\Sigma}^{-1} X\right)^{-1} X^{T} \hat{\Sigma}^{-1} y$

### 2.2 Proposed unit level Model

In the proposed model, we assume that unit specific auxiliary data $X_{j d}=\left(1, x_{1}, j d, \cdots, x_{p-1}, j d\right)$ are available for each population element $d$ in each small area $j$. Further, variable of interest $y_{j d}$, is assumed to follow lognormal distribution and to be related to $X_{j d}$ through a nested error nonparametric unit level model[5].

$$
\begin{equation*}
\log \left(y_{j d}\right):=l_{j d}=m\left(x_{j d}\right)+u_{j}+e_{j d} \tag{7}
\end{equation*}
$$

where the function $m(\cdot)$ is unknown, but estimated by Locally Weighted Scatterplot Smoothing (LOWESS) method and $\log \left(y_{j d}\right)$ is the response of unit $d, \quad d=1,2, \cdots, n_{j}$ in area $j, \quad j=1,2, \cdots, p, x_{j d}$ is the vector of auxiliary variables and The $u_{d}$ and $e_{j d}$ are mutually independent with zero mean and variance $\sigma_{u}^{2}$ and $\sigma_{e}^{2}$ respectively.

The small area parameter of interest, $\theta_{j}$, may be approximated by

$$
\begin{equation*}
\theta_{j}=m\left(\bar{X}_{j}\right)+v_{j}, \quad j=1, \cdots, p \tag{8}
\end{equation*}
$$

assuming that $N_{j}$ is large, where $\bar{X}_{j}$ is the average vector of population of the $x_{j d}$ for the jth area, that is, $\bar{X}_{j}=\sum_{d=1}^{N_{j}} x_{j d} / N_{j}$. The sample data $\left\{l_{j d}, x_{j d}, d=\right.$ $\left.1, \cdots, n_{j}, j=1, \cdots, p\right\}$ are assumed to obey model 7 , i.e.,

$$
\begin{equation*}
l_{j d}=m\left(x_{j d}\right)+v_{j}+e_{j d}, d=1, \cdots, n_{j}, \quad j=1, \cdots, p \tag{9}
\end{equation*}
$$

where $n_{j}$ is the sample size in the $j t h$ small area. This implies that the selection bias is absent. Assuming that $v_{j} \sim \mathcal{N}\left(0, \sigma_{u}^{2}\right), j=1, \cdots, p$ and expressing $l_{j d} \mid m\left(x_{j}\right), v_{j}, \sigma_{e}^{2} \sim \mathcal{N}\left(m\left(x_{j d}\right)+v_{j}, \sigma_{e}^{2}\right), d=1, \cdots, n_{j}, j=1, \cdots, p$, we have the distribution of $v_{j}$ from the model 9 conditional on $l_{j d}, m\left(x_{j}\right), \sigma_{u}^{2}$ and $\sigma_{e}^{2}$ as

$$
v_{j} \mid l_{j d}, m\left(x_{j}\right), \sigma_{u}^{2}, \sigma_{e}^{2} \sim \mathcal{N}\left(B_{j}\left(\bar{l}_{j}-m\left(\bar{x}_{j}\right)\right), B_{j} \frac{\sigma_{e}^{2}}{n_{j}}\right)
$$

where $B_{j}=\sigma_{u}^{2} /\left(\sigma_{u}^{2}+n_{j}^{-1} \sigma_{e}^{2}\right),\left(\bar{l}_{j}, \bar{x}_{j}\right)$ are the sample means for the $j^{t} h$ area and the mean function is given by $m(\cdot)$.

Therefore,

$$
\begin{equation*}
\mathbb{E}\left[l_{j d}, m\left(x_{j}\right), \sigma_{u}^{2}, \sigma_{e}^{2}\right]=B_{j}\left(\bar{l}_{j}-m\left(\bar{x}_{j}\right)\right) \tag{10}
\end{equation*}
$$

Using equation 8 and 10 , we get the Bayes predictor of $\theta_{j}, \theta_{j}^{B}$ as

$$
\begin{align*}
\theta_{j}^{B} & =\mathbb{E}\left[\theta_{j} \mid l_{j d}, m\left(x_{j}\right), \sigma_{u}^{2}, \sigma_{e}^{2}\right] \\
& =\left(m\left(\bar{x}_{j}\right)+B_{j}\left(\bar{l}_{j}-m\left(\bar{x}_{j}\right)\right)\right.  \tag{11}\\
& =\left(1-B_{j}\right) m\left(\bar{x}_{j}\right)+B_{j}\left[\bar{l}_{j}+m\left(\bar{X}_{i}-\bar{x}_{i}\right)\right]
\end{align*}
$$

Replacing $m\left(\bar{x}_{j}\right), \sigma_{u}^{2}$ and $\sigma_{e}^{2}$ by $\widehat{m}\left(\bar{x}_{j}\right), \hat{\sigma}_{u}^{2}$ and $\hat{\sigma}_{e}^{2}$ respectively we obtain the Empirical Bayes predictor of $\theta_{j}, \theta_{j}^{E B}$

$$
\begin{equation*}
\theta_{j}^{E B}=\left(1-\hat{B}_{j}\right) \widehat{m}\left(\bar{x}_{j}\right)+\hat{B}_{j}\left[\bar{l}_{j}+\widehat{m}\left(\bar{X}_{j}-\bar{x}_{j}\right)\right] \tag{12}
\end{equation*}
$$

where $\hat{B}_{j}=\hat{\sigma}_{u}^{2} /\left(\hat{\sigma}_{u}^{2}+n_{j}^{-1} \hat{\sigma}_{e}^{2}\right)$ and $\widehat{m}(\cdot)$ is a mean function estimated using LOWESS.

## 3 Simulation Study

In our simulation study, the performance of the basic unit-level(FBH) and proposed model were checked using left skewed simulated data. The variable of interest $y_{i j}$ or $y_{j d}$ were randomly selected from Burr Distribution with parameters $(c=1, k=4$, rate $=1)$ and the covariate values $X_{i j}$ or $X_{j d}$ were generated from Poisson distribution of $\lambda=$ (5), for 30 small areas of sizes ( $n=1000, N=3000$ ) to satisfy the skewness condition for both models. The random errors and the random area effects are mutually independent with zero mean and variance $\sigma_{u}^{2}$ and $\sigma_{e}^{2}$ respectively for both models. The plots for both models using simulated data are shown in figure 2 and 3 .

## 4 Performance Criteria

For the performance of Empirical Bayes estimators were examined from two general standpoints: the accuracy of point estimates and Mean Square Error of the estimates. The former was checked through the relative errors and absolute relative errors of the Empirical Bayes estimates, the latter was estimated by similar Bootstrap Technique proposed by [3]. For the empirical
comparison of relative errors and absolute relative errors of the EB estimates, the following four different criteria recommended by the panel on small area estimates of population and income set up by the United States Committee on National Statistics in 1978, [4].

### 4.1 Empirical Comparison of Empirical Bayes Estimates

Suppose $e_{i T R}$ denotes the true income for the $i^{t h}$ area, and $e_{i}$ is any estimate of $e_{i T R} ; i=1 ; \cdots ; m$. Then

1 Average relative bias: $(A R B)=\frac{1}{m} \sum_{i=1}^{m}\left|\frac{e_{i}-e_{i T R}}{e_{i T R}}\right|$,
2 Average squared relative bias : $(A S R B)=\frac{1}{m} \sum_{i=1}^{m}\left(\frac{e_{i}-e_{i T R}}{e_{i T R}}\right)^{2}$,
3 Average absolute bias : $(A A B)=\frac{1}{m} \sum_{i=1}^{m}\left|e_{i}-e_{i T R}\right|$,

4 Average squared deviation : $(A S D)=\frac{1}{m} \sum_{i=1}^{m}\left(e_{i}-e_{i T R}\right)^{2}$.

### 4.2 Estimation of MSE Using Bootstrap Algorithm for the Basic Unit level Model

After getting the parameter $\hat{\beta}$ for the Basic unit-level model from the simulated data, we need to gauge the performance of the Basic unit-level model by estimating the mean-squared error of small area parameter $\theta_{i}^{E B}$. We have achieved this by using the bootstrap technique of [3]. This technique enables us to obtain a bias-corrected, mean-squared error estimator of $\theta_{i}^{E B}$. We generated 100 bootstrap samples at each level of the bootstrap as described in the algorithm below:

$$
\begin{aligned}
& \text { 1.Do this } k_{1}=1 ; \cdots ; K_{1} \text { times } \\
& \text { generate } x_{b_{1}}^{*} \text { from } \mathcal{P}(n=1000, \lambda=5)
\end{aligned}
$$

$$
\begin{gathered}
\text { generate } y_{b_{1}}^{*} \text { from } \operatorname{rburr}(n=1000,1,4,1) \\
\text { get } \hat{\beta}_{b_{1}}^{*} \quad \text { from the bootstrap data }\left(y_{b_{1}}^{*} ; x_{b_{1}}^{*}\right) \\
\text { calculate } v_{b 1}^{*}=y_{b 1}^{*}-\bar{X}_{b 1}^{T *} \beta_{b 1}^{*} \\
\text { calculate } e_{b 1}^{*}=y_{b 1}^{*}-x_{b 1}^{*} \beta_{b 1}^{*}-v_{b 1}^{*} \\
\text { calculate } \theta_{b_{1}}^{*}\left(\hat{\beta}_{b 1}^{*}\right)=\bar{X}_{b 1}^{*} \hat{\beta}_{b 1}^{*}+v_{b_{1}}^{*} \\
\text { calculate } \quad \hat{\theta}_{b_{1}}^{* E B P}=\bar{X}_{b_{1}}^{*} \hat{\beta}_{b_{1}}^{*}+\hat{\Omega}\left[\bar{y}_{b_{1}}^{*}+\left(\bar{X}_{b_{1}}^{*}-\bar{x}_{b_{1}}^{*}\right)^{T} \hat{\beta}_{b_{1}}^{*}\right]
\end{gathered}
$$

Finally, the Mean Sum square is obtained as:

$$
(\widehat{M S E})=\frac{1}{K_{1}} \sum_{k_{1}=1}^{K_{1}}\left(\hat{\theta}_{b_{1}}^{* E B P}-\theta_{b_{1}}^{*}\left(\hat{\beta}_{b_{1}}^{*}\right)\right)^{2}
$$

### 4.3 Estimation of MSE Using Bootstrap Technique for the Proposed Model

After generating skewed data, the proposed model was used. We considered the span/bandwidth of 0.5 to tackle the issue of over and underestimation, more details [5]. The LOWESS (Locally Weighted Scatterplot Smoothing) method was used to estimate the mean function $m(\cdot)$ of the proposed model. The performance of the proposed model was measured by estimating the mean squared error of small area $\theta_{j}^{E B}$. We have achieved this by using the bootstrap technique of [3]. This technique enables us to obtain a bias-corrected, meansquared error estimator of $\theta_{j}^{E B}$. We generated 100 bootstrap samples at each level of the bootstrap as described in the algorithm below:

$$
\begin{aligned}
& \text { 1.Do this } k_{1}=1 ; \cdots ; K_{1} \text { times } \\
& \text { generate } x_{b_{1}}^{*} \text { from } \mathcal{P}(n=1000, \lambda=5) \\
& \text { generate } y_{b_{1}}^{*} \text { from } \operatorname{rburr}(n=1000,1,4,1) \\
& \text { calculate } v_{b 1}^{*}=l_{b 1}^{*}-m\left(\bar{X}_{b 1}^{*}\right) ;
\end{aligned}
$$

$l_{b 1}^{*}=\log \left(y_{b 1}^{*}\right)$
calculate $\quad \mathrm{e}_{b 1}^{*}=l_{b 1}^{*}-m\left(x_{b 1}\right)^{*}-v_{b 1}^{*}$
calculate $\quad \theta_{b_{1}}^{*}=m\left(\bar{X}_{b 1}^{*}\right)+v_{b_{1}}^{*}$
calculate $\quad \hat{\theta}_{b_{1}}^{* E B P}=m\left(\bar{X}_{b_{1}}^{*}\right)+\hat{B}\left[\bar{l}_{b_{1}}^{*}+m\left(\bar{X}_{b_{1}}^{*}-\bar{x}_{b_{1}}^{*}\right)\right]$

Finally, the Mean Sum square is obtained as:
$(\widehat{M S E})=\frac{1}{K_{1}} \sum_{k_{1}=1}^{K_{1}}\left(\hat{\theta}_{b_{1}}^{* E B P}-\theta_{b_{1}}^{*}\right)^{2}$

## 5 Simulation Results

In this section, we presented the results from the simulation study and their corresponding discussions.

The figure 1 presents the sampled simulated data for $i=1,6,17,24,28,30$ small areas. The maximum income is 40000 and the maximun number of members in household is 15 for $i=1$. We have simulated data for $i=1, \cdots, 30$.

The figure 2 describes the fitted data using the basic unit-level model(FBH). The model uses the linear method to fit the simulated data for $i=1, \cdots, 30$, it is uses the average income and average household members in for $i=1, \cdots, 30$ in all small areas.

The figure 3 describes the fitted data using the proposed model. The model uses the LOWESS (Locally Weighted Scatterplot Smoothing) method to fit the simulated data for $j=1, \cdots, 30$, by averaging income and average household members in for $j=1, \cdots, 30$ in all small areas.


Figure 1: Plot of the sampled simulated data

Table 1: Empirical Comparison of EB Estimates under Standard unit level $\operatorname{Model}(\mathrm{FBH})$ and Proposed Model (PM) at span $=0.5$ for skewed data using Four Different Criteria.

| Models | Average <br> Absolute <br> relative <br> bias | Average <br> squared <br> relative <br> bias | Average <br> Absolute <br> Bias | Average <br> Squared <br> Deviation |
| :--- | :--- | :--- | :--- | :--- |
| PM | 0.001228593 | 0.000002633468 | 0.01131202 | 0.0002229792 |
| FBHM | 0.01206998 | 0.0002286032 | 1.344029 | 2.832072 |



Figure 2: Fitted of Simulated data using basic unit-level model(FBH)


Figure 3: Fitted Simulated data using proposed model

The simulation results obtained for both models using the skewed data is presented in Table 1.

Table 2: Plot of empirical values of MSE using bootstrap approach: Comparison of the basic unit-level model(FBH) and the proposed model at span $=$ 0.5

| $\begin{array}{l}\text { Bootstrap } \\ \text { iterations }\end{array}$ | FBH |
| :--- | :---: | :---: |
| model |  |\(\left.\quad \begin{array}{c}Proposed <br>


model\end{array}\right]\)| 10 | 31380.69 | 0.0004 |
| :--- | :--- | :--- |
| 50 | 34580.97 | 0.00041 |
| 80 | 31455.222 | 0.00038 |
| 100 | 33739.27 | 0.00039 |

Table 2 MSE for both models obtained via the bootstrap approach.

## 6 Discussion of Results

The study was to investigate how the small area parameters $\theta$ would be affected under simulated data using the two models. We have compared the results of the Basic unit-level model and proposed a model on the basis of average absolute relative bias, average squared relative bias, average absolute bias and average squared deviation under the simulation setting where data simulated is left-skewed data for both models. Table 1 reports the values of these measures of empirical comparison. The results appear to suggest a better fit for the proposed method compared to the standard unit-level model(FBH). Table 2 provides a clear comparison of the basic unit-level model(FBH) and the proposed model in terms of empirical MSE obtained via the bootstrap approach proposed by [3], however, the double bootstrap method of Hall and Maiti (2006) could provide a better MSE estimator in terms of relative bias, but for large populations this method might not be computationally feasible[9]. The empirical value of MSE over 100 bootstrap iterations were obtained for $i=1, \cdots, 30$ small area. We see that the proposed model is markedly better than the basic unit-level model $(\mathrm{FBH})$ at span $=0.5$ in each bootstrap iterations.

## 7 Conclusion

Assuming the normal assumptions are not satisfied within the small area unit, the proposed model at span $=0.5$ appears to perform well compared to the standard unit-level model. However, more research is needed to integrate the non-parametric methods into small area estimation. We are currently working on the performance of the proposed model under the hierarchical Bayes approach.

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